

# LOFT: Finding Lottery Tickets through Filter-wise Training

Qihan Wang\*, Chen Dun\*, Fangshuo Liao\*, Chris Jermaine, Anastasios Kyrillidis

\*Equal Contribution



## NEW METRIC FOR FILTER DISTANCE

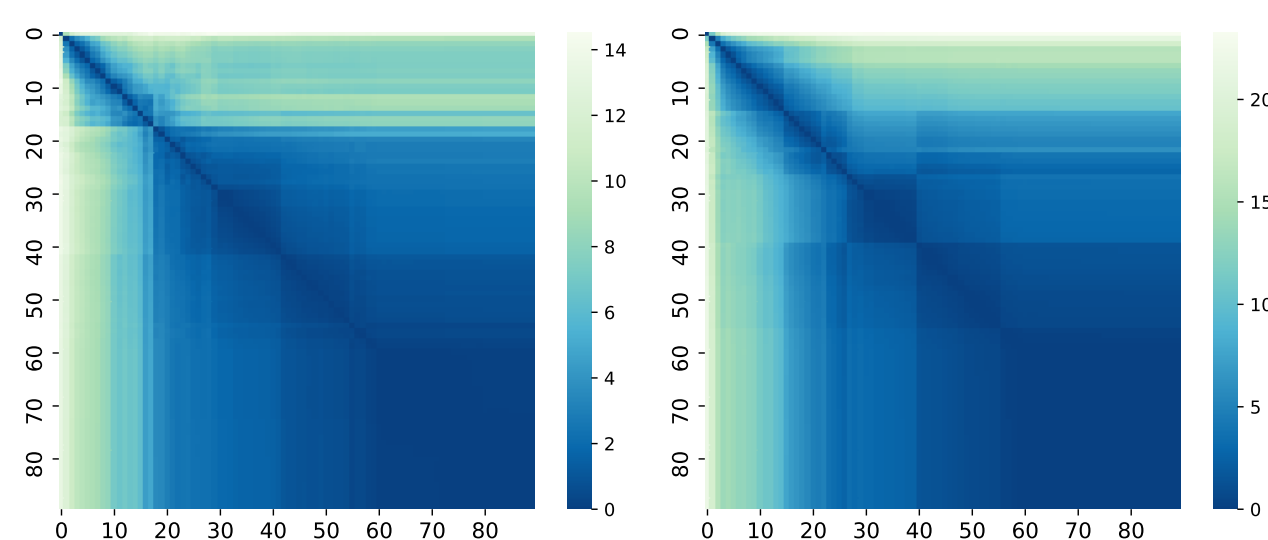
Let  $\mathcal{R}$  and  $\hat{\mathcal{R}}$  be two rankings of the filters. Let  $\sigma : \mathcal{R} \rightarrow \hat{\mathcal{R}}$  such that  $\sigma(\mathcal{R}_i) = \hat{\mathcal{R}}_i$ . We introduce a new metric to measure filter similarity based on Spearman's footrule

$$F_{\text{filter}}(\sigma) = \sum_i \frac{1}{i} \cdot |\ln(i) - \ln(\sigma(i))|$$

### Properties of the Metric

- $\ln(\cdot)$  is used to approximate the summation.
- $|\ln(i) - \ln(\sigma(i))|$  is larger if  $i$  is significantly different from  $\sigma(i)$
- $\frac{1}{i}$  puts larger weight on filters with higher ranking in  $\mathcal{R}$

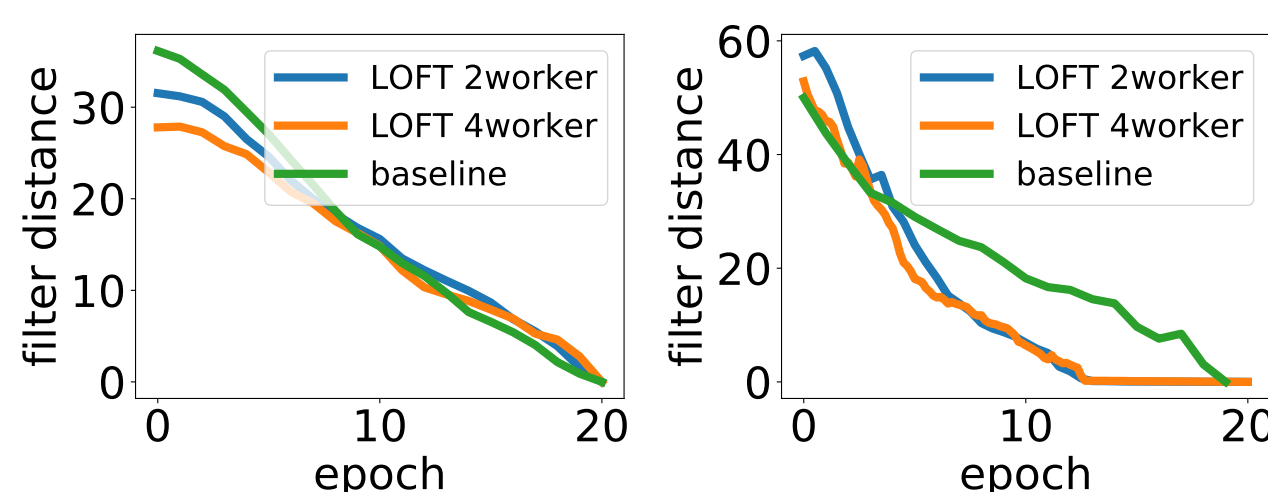
Winning tickets appears before loss converges (darker=smaller distance)



conv-layer-2 conv-layer-4

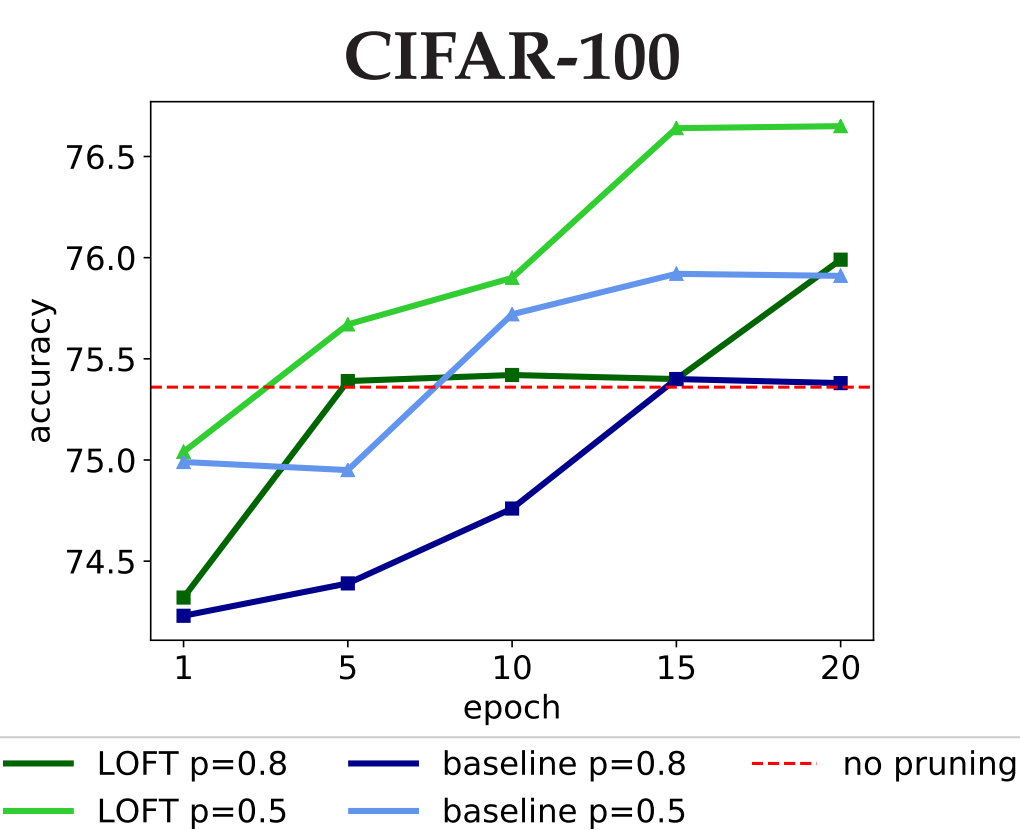
## FINDING WINNING TICKETS FASTER

Filter distance between filter during training and the winning filter



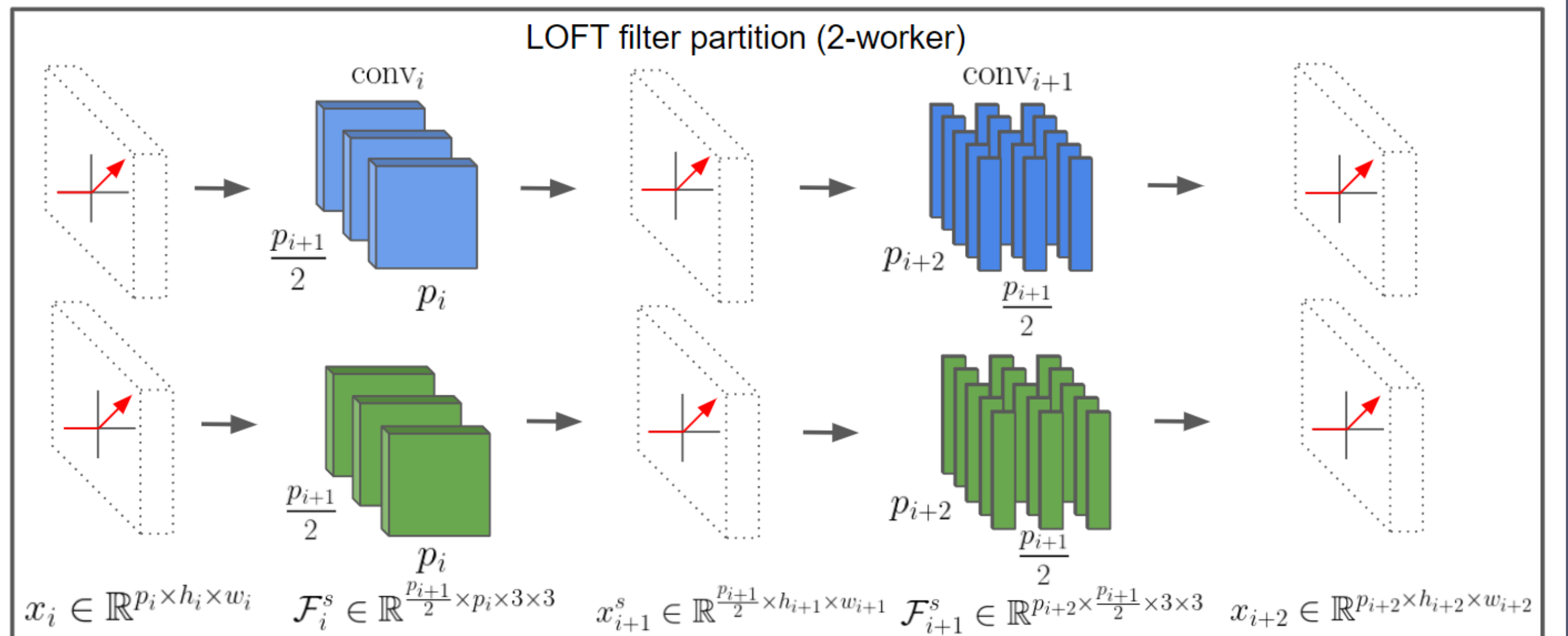
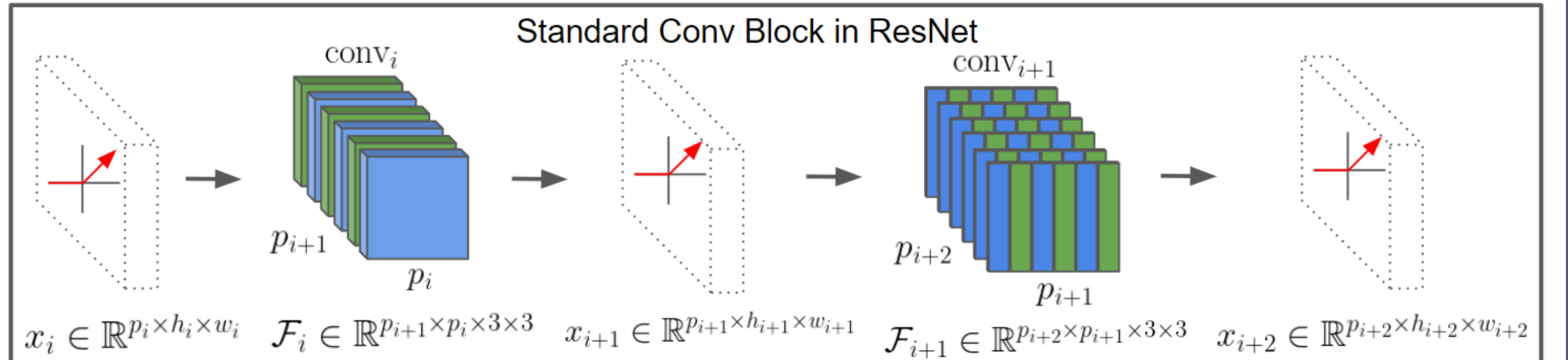
CIFAR-100 ImageNet

Evaluate Snapshots of Tickets during Training by Rewinding & Retraining



## LOFT: INTUITION AND APPROACH

- Training until loss convergence is not necessary for finding winning tickets
- LoFT: an algorithm that sacrifice some loss convergence property but can be trained efficiently in distributed fashion



Each worker holds a smaller filter and a subset of the channels in the hidden layers.

Each subnetwork can be trained for multiple local iterations.

Input and output layer is not partitioned.

## LOFT ACHIEVES LOWER COMMUNICATION COST

SETTING	NO-PRUNE	METHODS	PRUNING RATIO			COMM COST	IMPROV.
			80%	50%	30%		
PRERESNET-34 CIFAR-10	93.51	GPIPE-2	93.93	94.38		131.88G	
		LOFT-2	93.25	93.43		104.59G	1.26×
		GPIPE-4	93.93	94.38		461.60G	
		LOFT-4	93.89	94.02		144.27G	3.20×
RESNET-34 CIFAR-10	93.22	GPIPE-2	93.69	93.81		131.88G	
		LOFT-2	93.38	93.41		104.60G	1.26×
		GPIPE-4	93.69	93.81		461.60G	
		LOFT-4	93.41	93.60		144.29G	3.20×
PRERESNET-34 CIFAR-100	76.57	GPIPE-2	76.72	77.09		131.88G	
		LOFT-2	75.93	77.27		104.77G	1.26×
		GPIPE-4	76.72	77.09		461.60G	
		LOFT-4	75.77	76.79		144.64G	3.19×
RESNET34 CIFAR-100	75.93	GPIPE-2	75.51	76.00		131.88G	
		LOFT-2	76.11	77.07		104.78G	1.26×
		GPIPE-4	75.51	76.00		461.60G	
		LOFT-4	75.05	76.51		144.66G	3.19×
PRERESNET-18 IMAGENET	70.71	GPIPE-2	66.71	69.14	70.29	20954.24G	
		LOFT-2	65.41	69.12	69.64	791.09G	21.60×
		GPIPE-4	66.71	69.14	70.29	52385.59G	
		LOFT-4	65.60	68.93	69.77	1284.84G	40.77×

## THEORETICAL RESULT: LOFT TRAJECTORY STAYS NEAR GD TRAJECTORY

Let  $\mathbf{X} \in \mathbb{R}^{n \times d \times p}$  be the input data and  $\mathbf{y} \in \mathbb{R}^n$  be the labels. Let  $f$  be a one-hidden-layer CNN with only the first layer filters  $\mathbf{W}$  trainable. Let  $\{\mathbf{W}_t\}_{t=0}^T$  and  $\{\hat{\mathbf{W}}_t\}_{t=0}^T$  be the weights in the trajectory of LOFT and GD. Let  $S$  be the number of workers.

**Theorem 1.** Assume the number of hidden filters satisfies  $m = \Omega\left(\frac{n^4 T^2}{\lambda_0^2 \delta^2} \max\{n, d\}\right)$  and the step size satisfies  $\eta = O\left(\frac{\lambda_0}{n^2}\right)$ . Then, with probability at least  $1 - O(\delta)$  we have:

$$\mathbb{E}_{[\mathbf{M}_T]} \left[ \left\| \mathbf{W}_T - \hat{\mathbf{W}}_T \right\|_F^2 \right] + \eta \sum_{t=0}^{T-1} \mathbb{E}_{[\mathbf{M}_T]} \left[ \left\| f(\mathbf{X}, \mathbf{W}_t) - f(\mathbf{X}, \hat{\mathbf{W}}_t) \right\|_2^2 \right] \leq O\left( \frac{n^2 \sqrt{d}}{\lambda_0^2 \kappa m^{\frac{1}{4}} \sqrt{\delta}} + \frac{2\eta^2 T \theta^2 (1-\xi) \lambda_0}{S} \right).$$